ABSTRACT OF THE DISCLOSURE

A driving assistance apparatus includes: cameras; a plurality of virtual observing point converting unit; an image synthesizing unit for synthesizing image information supplied from this virtual observing point converting unit; an obstacle sensing unit such as an ultrasonic-wave sensor and a millimeter-wave radar; a safety area predicting unit; and a safety area superposing unit. Then, the safety area predicting unit predicts such a safety area where an obstacle is not present based upon both a distance "d1" and an approximate direction, which are obtained from the obstacle sensing unit. Also, the safety area superposing unit superposes the safety area predicted by the safety area predicting unit on an image synthesized by way of cameras to display the synthesized image superposed with the safety area.